

Extracting a Data Flow Analyser in Constructive Logic

David Cachera, Thomas Jensen, David Pichardie and Vlad Rusu

APPSEM'04, Tallinn



institut de recherche en informatique
et systèmes aléatoires



Static program analysis

The goals of static program analysis

- ▶ To prove properties about the run-time behaviour of a program
- ▶ In a fully automatic way
- ▶ Without actually executing this program

Static program analysis

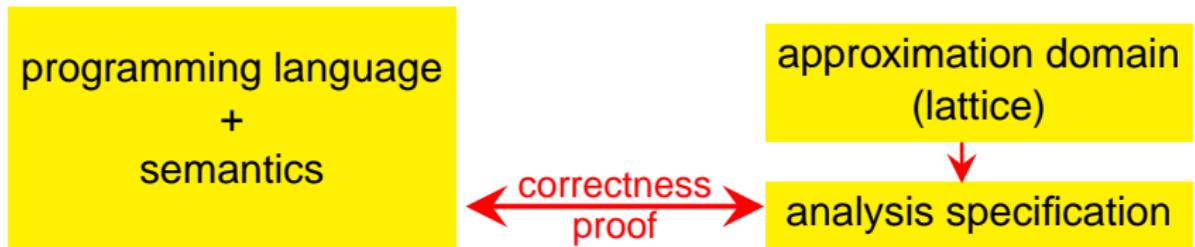
The goals of static program analysis

- ▶ To prove properties about the run-time behaviour of a program
- ▶ In a fully automatic way
- ▶ Without actually executing this program

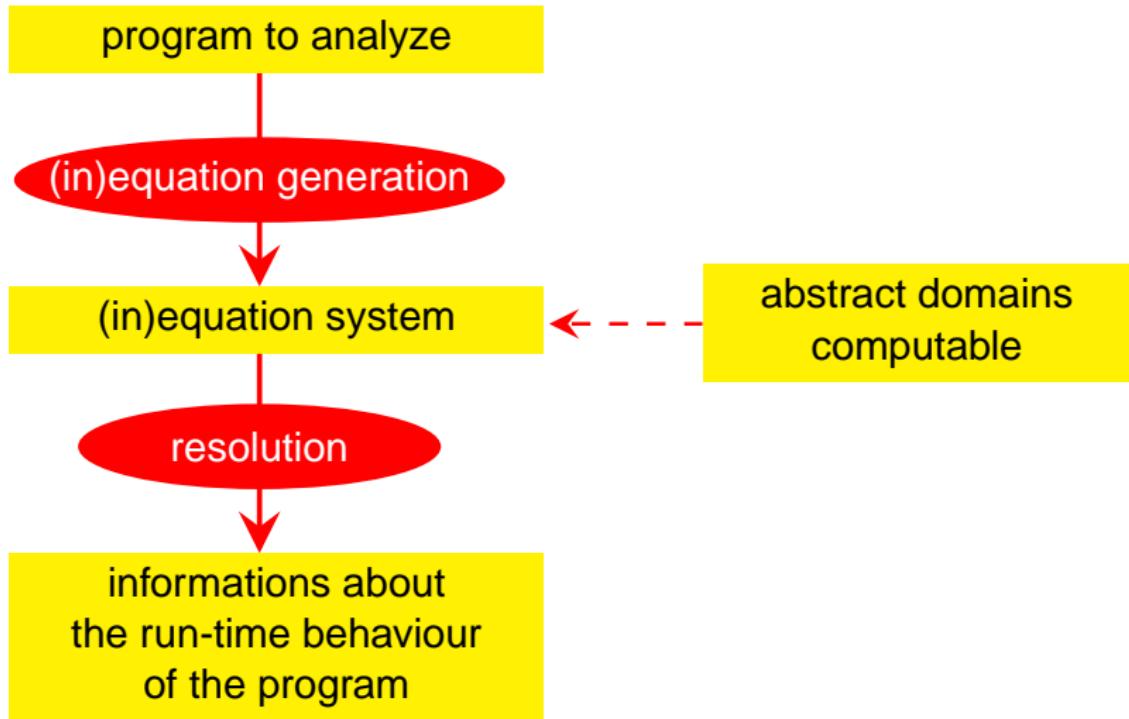
Solid foundations for designing an analyser

- ▶ Formalization and correctness proof by abstract interpretation
- ▶ Resolution of constraints on lattices by iteration and symbolic computation

Formalization



Resolution



So what's the problem ?

Formalization part

$$\begin{aligned}
& \dot{\alpha}[P](\text{Post}[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}]) \\
= & \quad \{\text{def. (110) of } \dot{\alpha}[P]\} \\
& \dot{\alpha}[P] \circ \text{Post}[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}] \circ \dot{\gamma}[P] \\
= & \quad \{\text{def. (103) of Post}\} \\
& \dot{\alpha}[P] \circ \text{post}[\tau^*[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}]] \circ \dot{\gamma}[P] \\
= & \quad \{\text{big step operational semantics (93)}\} \\
& \dot{\alpha}[P] \circ \text{post}[(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_t] \circ (1_{\Sigma[P]} \cup \tau^t) \cup (1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_f] \circ (1_{\Sigma[P]} \cup \tau^f)] \circ \dot{\gamma}[P] \\
= & \quad \{\text{Galois connection (98) so that post preserves joins}\} \\
& \dot{\alpha}[P] \circ (\text{post}[(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_t] \circ (1_{\Sigma[P]} \cup \tau^t)]) \cup \text{post}[(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_f] \circ (1_{\Sigma[P]} \cup \tau^f)] \circ \dot{\gamma}[P] \\
= & \quad \{\text{Galois connection (106) so that } \dot{\alpha}[P] \text{ preserves joins}\} \\
& (\dot{\alpha}[P] \circ \text{post}[(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_t] \circ (1_{\Sigma[P]} \cup \tau^t)]) \circ \dot{\gamma}[P] \quad \dot{\cup} \quad (\dot{\alpha}[P] \circ \text{post}[(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_f] \circ (1_{\Sigma[P]} \cup \tau^f)]) \circ \dot{\gamma}[P] \\
\stackrel{?}{=} & \quad \{\text{lemma (5.3) and similar one for the else branch}\} \\
\lambda J \cdot \text{let } J' = & \lambda I \in \text{in}_P[P] \cdot (I = \text{at}_P[S_t] ? J_{\text{at}_P[S_t]} \dot{\cup} \text{Abexp}[B](J_\ell) \wedge J_l) \text{ in} \quad (120) \\
& \text{let } J'^t = \text{APost}[S_t](J') \text{ in} \\
& \quad \lambda I \in \text{in}_P[P] \cdot (I = \ell' ? J'^t_{\ell'} \dot{\cup} J'^t_{\text{after}_P[S_t]} \wedge J'^t_l) \\
\stackrel{?}{=} & \quad \text{let } J'^f = \lambda I \in \text{in}_P[P] \cdot (I = \text{at}_P[S_f] ? J_{\text{at}_P[S_f]} \dot{\cup} \text{Abexp}[T(\neg B)](J_\ell) \wedge J_l) \text{ in} \\
& \quad \text{let } J'^f = \text{APos}[S_f](J') \text{ in} \\
& \quad \lambda I \in \text{in}_P[P] \cdot (I = \ell' ? J'^f_{\ell'} \dot{\cup} J'^f_{\text{after}_P[S_f]} \wedge J'^f_l) \\
= & \quad \{\text{by grouping similar terms}\} \\
\lambda J \cdot \text{let } J' = & \lambda I \in \text{in}_P[P] \cdot (I = \text{at}_P[S_t] ? J_{\text{at}_P[S_t]} \dot{\cup} \text{Abexp}[B](J_\ell) \wedge J_l) \\
& \text{and } J'^t = \lambda I \in \text{in}_P[P] \cdot (I = \text{at}_P[S_f] ? J_{\text{at}_P[S_f]} \dot{\cup} \text{Abexp}[T(\neg B)](J_\ell) \wedge J_l) \text{ in} \\
& \quad \text{let } J'^t = \text{APost}[S_t](J') \\
& \quad \text{and } J'^f = \text{APos}[S_f](J') \text{ in} \\
& \quad \lambda I \in \text{in}_P[P] \cdot (I = \ell' ? J'^t_{\ell'} \dot{\cup} J'^t_{\text{after}_P[S_t]} \dot{\cup} J'^f_{\ell'} \dot{\cup} J'^f_{\text{after}_P[S_f]} \wedge J'^t_l \wedge J'^f_l) \\
= & \quad \{\text{by locality (113) and labelling scheme (59) so that in particular } J'^t_{\ell'} = J'_\ell = J'_\ell = J'^f_{\ell'} \\
& \quad = J'^f_{\ell'} \text{ and } \text{APost}[S_t] \text{ and } \text{APos}[S_f] \text{ do not interfere}\}
\end{aligned}$$

Formalization part

$$\begin{aligned}
 & \dot{\alpha}[P](\text{Post}[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}]) \\
 = & \quad \{\text{def. (110) of } \dot{\alpha}[P]\} \\
 & \dot{\alpha}[P] \circ \text{Post}[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}] \circ \dot{\gamma}[P] \\
 = & \quad \{\text{def. (103) of Post}\} \\
 & \dot{\alpha}[P] \circ \text{post}[\tau^*[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}]] \circ \dot{\gamma}[P] \\
 = & \quad \{\text{big step operational semantics (93)}\} \\
 & \dot{\alpha}[P] \circ \text{post}[(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_t] \circ (1_{\Sigma[P]} \cup \tau^t) \cup (1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_f] \circ (1_{\Sigma[P]} \cup \tau^f) \circ \dot{\gamma}[P]] \\
 = & \quad \{\text{Galois connection (98) so that post preserves joins}\} \\
 & \dot{\alpha}[P] \circ (\text{post}[(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_t] \circ (1_{\Sigma[P]} \cup \tau^t)]) \cup \\
 & \quad \text{post}[(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_f] \circ (1_{\Sigma[P]} \cup \tau^f)] \circ \dot{\gamma}[P] \\
 = & \quad \{\text{Galois connection (106) so that } \dot{\alpha}[P] \text{ preserves joins}\} \\
 & (\dot{\alpha}[P] \circ \text{post}[(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_t] \circ (1_{\Sigma[P]} \cup \tau^t)]) \cup \dot{\gamma}[P] \cup (\dot{\alpha}[P] \circ \\
 & \quad \text{post}[(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_f] \circ (1_{\Sigma[P]} \cup \tau^f)] \circ \dot{\gamma}[P]) \\
 \in & \quad \{\text{lemma (5.3) and similar one for the else branch}\} \\
 \lambda J \cdot \text{let } J' = J \in \text{in}_P[P] \cdot (l = \text{at}_P[S_t] ? J_{\text{at}_P[S_t]} \dot{\cup} \text{Abexp}[B](J_\ell) \wedge J_l) \text{ in} & (120) \\
 & \quad \text{let } J'^t = \text{APost}[S_t](J') \text{ in} \\
 & \quad \lambda l \in \text{in}_P[P] \cdot (l = \ell' ? J'^{\ell'}_{\ell'} \dot{\cup} J'^t_{\text{after}_P[S_t]} \wedge J^t_l) \\
 \in & \quad \{\text{grouping similar terms}\} \\
 \lambda J \cdot \text{let } J' = \lambda l \in \text{in}_P[P] \cdot (l = \text{at}_P[S_f] ? J_{\text{at}_P[S_f]} \dot{\cup} \text{Abexp}[T(\neg B)](J_\ell) \wedge J_l) \text{ in} \\
 & \quad \text{let } J'^f = \text{APos}[S_f](J') \text{ in} \\
 & \quad \lambda l \in \text{in}_P[P] \cdot (l = \ell' ? J'^{\ell'}_{\ell'} \dot{\cup} J'^f_{\text{after}_P[S_f]} \wedge J^f_l) \\
 = & \quad \{\text{by grouping similar terms}\} \\
 \lambda J \cdot \text{let } J' = \lambda l \in \text{in}_P[P] \cdot (l = \text{at}_P[S_t] ? J_{\text{at}_P[S_t]} \dot{\cup} \text{Abexp}[B](J_\ell) \wedge J_l) \\
 & \quad \text{and } J'^t = \lambda l \in \text{in}_P[P] \cdot (l = \text{at}_P[S_f] ? J_{\text{at}_P[S_f]} \dot{\cup} \text{Abexp}[T(\neg B)](J_\ell) \wedge J_l) \text{ in} \\
 & \quad \text{let } J'^t = \text{APos}[S_t](J') \\
 & \quad \text{and } J'^f = \text{APos}[S_f](J') \text{ in} \\
 & \quad \lambda l \in \text{in}_P[P] \cdot (l = \ell' ? J'^{\ell'}_{\ell'} \dot{\cup} J'^t_{\text{after}_P[S_t]} \dot{\cup} J'^f_{\text{after}_P[S_f]} \wedge J^t_l \wedge J^f_l) \\
 = & \quad \{\text{by locality (113) and labelling scheme (59) so that in particular } J'^{\ell'}_{\ell'} = J'_\ell = J^t_\ell = J^f_\ell \\
 & \quad = J^t_{\ell'} = J^f_{\ell'} \text{ and } \text{APos}[S_t] \text{ and } \text{APos}[S_f] \text{ do not interfere}\}
 \end{aligned}$$

©P. Cousot

Implementation part

```

int main(int argc, char **argv)
{
    int i, j, t, parent_a, parent_b;
    int **swap, **newpop, **oldpop;
    double *fit, *normfit;

    get_options(argc, argv, options, help_string);
    srand(seed);
    read_specs(specs);
    size += (size / 2 * 2 != size);
    newpop = xmalloc(sizeof(int *) * size);
    oldpop = xmalloc(sizeof(int *) * size);
    fit = xmalloc(sizeof(double) * size);
    normfit = xmalloc(sizeof(double) * size);
    for(i = 0; i < size; i++) {
        newpop[i] = xmalloc(sizeof(int) * len);
        oldpop[i] = xmalloc(sizeof(int) * len);
        for(j = 0; j < len * 2; j++)
            random_solution(oldpop[i]);
    }
    for(t = 0; t < gens; t++) {
        compute_fitness(oldpop, fit, normfit);
        dump_stats(t, oldpop, fit);
        for(i = 0; i < size; i += 2) {
            parent_a = select_one(normfit);
            parent_b = select_one(normfit);
            reproduce(oldpop, newpop, parent_a, parent_b, i);
        }
        swap = newpop; newpop = oldpop; oldpop = swap;
    }
    exit(0);
}

```

Formalization part

$$\begin{aligned}
 & \dot{\alpha}[P](\text{Post}[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}]) \\
 = & \quad \{\text{def. (110) of } \dot{\alpha}[P]\} \\
 & \dot{\alpha}[P] \circ \text{Post}[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}] \circ \dot{\gamma}[P] \\
 = & \quad \{\text{def. (103) of Post}\} \\
 & \dot{\alpha}[P] \circ \text{post}[\tau^*[\text{if } B \text{ then } S_t \text{ else } S_f \text{ fi}]] \circ \dot{\gamma}[P] \\
 = & \quad \{\text{big step operational semantics (93)}\} \\
 & \dot{\alpha}[P] \circ \text{post}[(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_t] \circ (1_{\Sigma[P]} \cup \tau^t) \cup (1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_f] \circ (1_{\Sigma[P]} \cup \\
 & \quad \tau^f)] \circ \dot{\gamma}[P] \\
 = & \quad \{\text{Galois connection (98) so that post preserves joins}\} \\
 & \dot{\alpha}[P] \circ (\text{post}[(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_t] \circ (1_{\Sigma[P]} \cup \tau^t)] \cup \\
 & \quad \text{post}[(1_{\Sigma[P]} \cup \tau^B) \circ \tau^*[S_f] \circ (1_{\Sigma[P]} \cup \tau^f)]) \circ \dot{\gamma}[P] \\
 = & \quad \{\dot{\alpha}[\text{pos}]\} \\
 \vdash & \quad \{\text{by locality (113) and labelling scheme (59) so that in particular } J'_e = J'_e = J'_e = J'_e \\
 & \quad = J'_e = J'_e \text{ and } \text{APost}[S_t] \text{ and } \text{APost}[S_f] \text{ do not interfere}\}
 \end{aligned}$$

Do both parts talk about the same ?

$$\begin{aligned}
 & \lambda J \cdot \text{let } J' = \lambda I \in \text{in}_P[P] \cdot (I = \text{at}_P[S_t] ? J_{\text{at}_P[S_t]} \dot{\cup} \text{Abexp}[B](J_e) \& J_l) \text{ in} \quad (120) \\
 & \quad \text{let } J'' = \text{APost}[S_t](J') \text{ in} \\
 & \quad \lambda I \in \text{in}_P[P] \cdot (I = \ell' ? J'_e \dot{\cup} J''_{\text{after}_P[S_t]} \& J'_l) \\
 & \quad \vdash \\
 & \text{let } J' = \lambda I \in \text{in}_P[P] \cdot (I = \text{at}_P[S_f] ? J_{\text{at}_P[S_f]} \dot{\cup} \text{Abexp}[T(\neg B)](J_e) \& J_l) \text{ in} \\
 & \quad \text{let } J'' = \text{APost}[S_f](J') \text{ in} \\
 & \quad \lambda I \in \text{in}_P[P] \cdot (I = \ell' ? J''_e \dot{\cup} J''_{\text{after}_P[S_f]} \& J''_l) \\
 = & \quad \{\text{by grouping similar terms}\} \\
 & \lambda J \cdot \text{let } J' = \lambda I \in \text{in}_P[P] \cdot (I = \text{at}_P[S_t] ? J_{\text{at}_P[S_t]} \dot{\cup} \text{Abexp}[B](J_e) \& J_l) \\
 & \quad \text{and } J'' = \lambda I \in \text{in}_P[P] \cdot (I = \text{at}_P[S_f] ? J_{\text{at}_P[S_f]} \dot{\cup} \text{Abexp}[T(\neg B)](J_e) \& J_l) \text{ in} \\
 & \quad \text{let } J' = \text{APost}[S_t](J') \\
 & \quad \text{and } J'' = \text{APost}[S_f](J') \text{ in} \\
 & \quad \lambda I \in \text{in}_P[P] \cdot (I = \ell' ? J'_e \dot{\cup} J''_{\text{after}_P[S_t]} \dot{\cup} J''_e \dot{\cup} J''_{\text{after}_P[S_f]} \& J'_l \& J''_l)
 \end{aligned}$$

©P. Cousot

Implementation part

```

int main(int argc, char **argv)
{
    int i, j, t, parent_a, parent_b;
    int **swap, **newpop, **oldpop;
    double *fit, *normfit;

    get_options(argc, argv, options, help_string);
    srand(seed);
    read_specs(specs);
    size += (size / 2 * 2 != size);
    newpop = xmalloc(sizeof(int *) * size);

    oldpop[i] = xmalloc(sizeof(int) * len);
    for(j = 0; j < len * 2; j++)
        random_solution(oldpop[i]);
}

for(t = 0; t < gens; t++) {
    compute_fitness(oldpop, fit, normfit);
    dump_stats(t, oldpop, fit);
    for(i = 0; i < size; i += 2) {
        parent_a = select_one(normfit);
        parent_b = select_one(normfit);
        reproduce(oldpop, newpop, parent_a, parent_b, i);
    }
    swap = newpop; newpop = oldpop; oldpop = swap;
}
exit(0);
}

```

Static Analysis for real-life languages

Example of real-life language : bytecode JavaCard

- ▶ 180 instructions
- ▶ Real need of static analysis to verify properties about security, memory management, ...

For this kind of languages,

- ▶ Abstract domains can be complex
- ▶ Correctness proofs become long and tiresome
- ▶ Implementation and maintenance of the analyser become a software engineering task

In this work

We propose a technique based on the Coq proof assistant

- ▶ To specify a static analysis,
- ▶ To prove its correctness wrt. the semantics of the language,
- ▶ To extract a static analyser from the proof of existence of a correct program analysis result

Program-as-proofs paradigm:

Write a function f which
verifies a specification P
 $\forall x, P(x, f(x))$



Make a constructive proof
of $\forall x, \exists y, P(x, y)$

Outline

- ▶ Motivation
- ▶ A Static Analysis for Carmel
- ▶ Building a certified static analyser
- ▶ Conclusion

Outline

- ▶ Motivation
- ▶ A Static Analysis for Carmel
- ▶ Building a certified static analyser
- ▶ Conclusion

Case study : a static analysis for Carmel

We follow the analysis proposed by René Rydhof Hansen¹

- ▶ Carmel : an intermediate representation of Java Card byte code
- ▶ Construction of a certified data flow analyser for Carmel

¹René Rydhof Hansen. Flow Logic for Carmel. SECSAFE-IMM-001, 2002

Syntax of Carmel

Instruction ::=

- nop
 - push *c*
 - pop
 - numop *op*
 - load *x*
 - store *x*
 - if *pc*
 - goto *pc*
 - new *cl*
 - putfield *f*
 - getfield *f*
 - invokevirtual *m_{id}*
 - return
-
- The diagram illustrates the classification of Carmel instructions into five categories, each indicated by a brace:
- stack manipulation: push, pop, numop
 - local variables manipulation: load, store
 - jump: if, goto
 - heap manipulation: new, putfield, getfield
 - method call and return: invokevirtual, return

Semantic domains

Val	::=	num n	$n \in \mathbb{N}$
		ref r	$r \in \text{Reference}$
		null	
Stack	=	Val*	
LocalVar	=	Var \rightarrow Val	
Frame	=	PointProg \times NameMethod \times LocalVar \times Stack	
CallStack	=	Frame*	
Object	=	FieldName \rightarrow Val	
Heap	=	Reference \rightarrow Object $_{\perp}$	
State	=	Heap \times CallStack	

Example :

$$(H, \langle m, pc, L, v :: S \rangle :: SF)$$

Dynamic semantics

Operational semantics with rules like

$$\frac{\text{instructionAt}_P(m, pc) = \text{push } c}{(H, \langle m, pc, L, S \rangle :: SF) \Rightarrow (H, \langle m, pc + 1, L, c :: S \rangle :: SF)}$$

$$\frac{\begin{array}{l} \text{instructionAt}_P(m, pc) = \text{invokevirtual } m_{id} \\ m' = \text{methodLookup}(m_{id}, h(loc)) \\ f' = \langle m', 1, V, \varepsilon \rangle \\ f'' = \langle m, pc, l, s \rangle \end{array}}{(h, \langle m, pc, l, loc :: V :: s \rangle :: sf) \Rightarrow (h, f' :: f'' :: sf)}$$

A Static Analysis for Carmel

We want to calculate an approximation $(\hat{H}, \hat{L}, \hat{S})$ on the domain

$$\begin{aligned}\widehat{\text{State}} = \widehat{\text{Heap}} & \times \left(\text{NameMethod} \times \text{PointProg} \rightarrow \widehat{\text{LocalVar}} \right) \\ & \times \left(\text{NameMethod} \times \text{PointProg} \rightarrow \widehat{\text{Stack}} \right)\end{aligned}$$

- ▶ An approximation for all reachable heaps
- ▶ For each program points, an approximation of the operand stack and the local variables
- ▶ An object is abstracted to its class
- ▶ Numeric values are abstracted using Killdall's Constant Propagation domain

Analysis specification

Each instruction impose constraints on $(\hat{H}, \hat{L}, \hat{S})$.

Example

- 0 : push 1
- 1 : push 2
- 2 : store 0
- 3 : load 0
- 4 : numop mult
- 5 : goto 1

Analysis specification

Each instruction impose constraints on $(\hat{H}, \hat{L}, \hat{S})$.

Example

0 : push 1

$$\hat{\text{nil}} \sqsubseteq \hat{S}(m, 0)$$

$$\top \sqsubseteq \hat{L}(m, 0)$$

→ 1 : push 2

2 : store 0

3 : load 0

4 : numop mult

5 : goto 1

Analysis specification

Each instruction impose constraints on $(\hat{H}, \hat{L}, \hat{S})$.

Example

0 : push 1

$$\hat{\text{nil}} \sqsubseteq \hat{S}(m, 0)$$

$$\top \sqsubseteq \hat{L}(m, 0)$$

1 : push 2

$$\widehat{\text{push}}(\hat{1}, \hat{S}(m, 0)) \sqsubseteq \hat{S}(m, 1)$$

$$\hat{L}(m, 0) \sqsubseteq \hat{L}(m, 1)$$

2 : store 0

3 : load 0

4 : numop mult

5 : goto 1

Analysis specification

Each instruction impose constraints on $(\hat{H}, \hat{L}, \hat{S})$.

Example

0 : push 1

$$\text{nil} \sqsubseteq \hat{S}(m, 0)$$

$$\top \sqsubseteq \hat{L}(m, 0)$$

1 : push 2

$$\widehat{\text{push}}(\hat{1}, \hat{S}(m, 0)) \sqsubseteq \hat{S}(m, 1)$$

$$\hat{L}(m, 0) \sqsubseteq \hat{L}(m, 1)$$

2 : store 0

$$\widehat{\text{push}}(\hat{2}, \hat{S}(m, 1)) \sqsubseteq \hat{S}(m, 2)$$

$$\hat{L}(m, 1) \sqsubseteq \hat{L}(m, 2)$$

3 : load 0

$$\widehat{\text{pop}}(\hat{S}(m, 2)) \sqsubseteq \hat{S}(m, 3)$$

$$\hat{L}(m, 2)[0 \mapsto \widehat{\text{top}}(\hat{S}(m, 2))] \sqsubseteq \hat{L}(m, 3)$$

4 : numop mult

$$\widehat{\text{push}}(\hat{L}(m, 3)[0], \hat{S}(m, 3)) \sqsubseteq \hat{S}(m, 4)$$

$$\hat{L}(m, 3) \sqsubseteq \hat{L}(m, 4)$$

5 : goto 1

...

$$\hat{L}(m, 4) \sqsubseteq \hat{L}(m, 5)$$

$$\hat{S}(m, 5) \sqsubseteq \hat{S}(m, 1)$$

$$\hat{L}(m, 5) \sqsubseteq \hat{L}(m, 1)$$

Analysis solution

The smallest value which verifies all constraints.

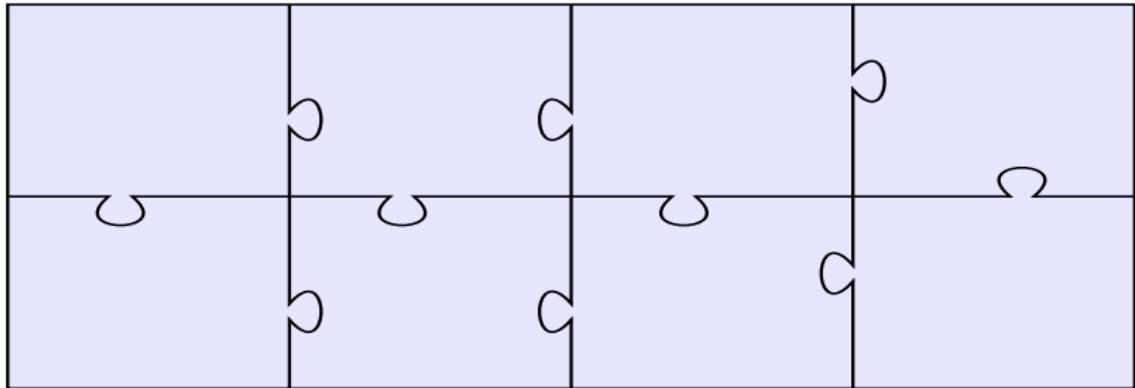
Example

0 : push 1	$\hat{\text{nil}}$	$[0 \mapsto \top; 1 \mapsto \top]$
1 : push 2	$\langle \hat{2} \rangle$	$[0 \mapsto \hat{1}; 1 \mapsto \top]$
2 : store 0	$\langle \hat{1} :: \hat{2} \rangle$	$[0 \mapsto \hat{1}; 1 \mapsto \top]$
3 : load 0	$\langle \hat{2} \rangle$	$[0 \mapsto \hat{1}; 1 \mapsto \top]$
4 : numop mult	$\langle \hat{1} :: \hat{2} \rangle$	$[0 \mapsto \hat{1}; 1 \mapsto \top]$
5 : goto 1	\perp	\perp

Outline

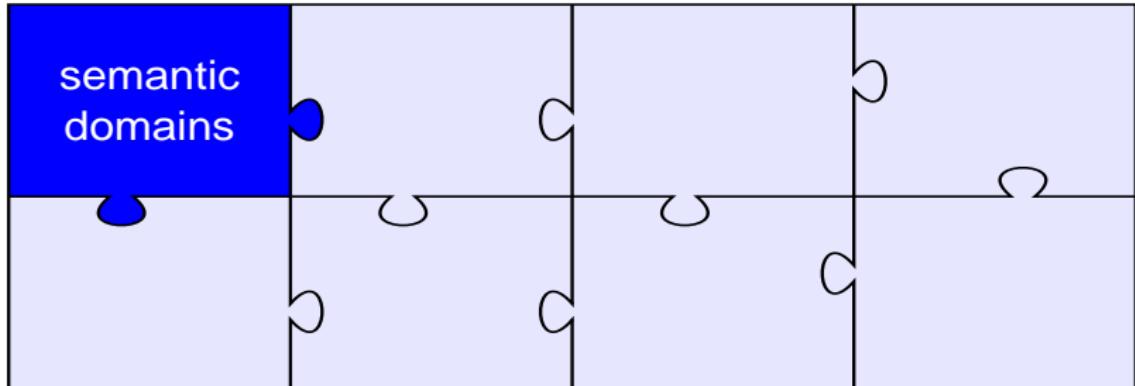
- ▶ Motivation
- ▶ A Static Analysis for Carmel
- ▶ Building a certified static analyser
- ▶ Conclusion

Building a certified static analyser



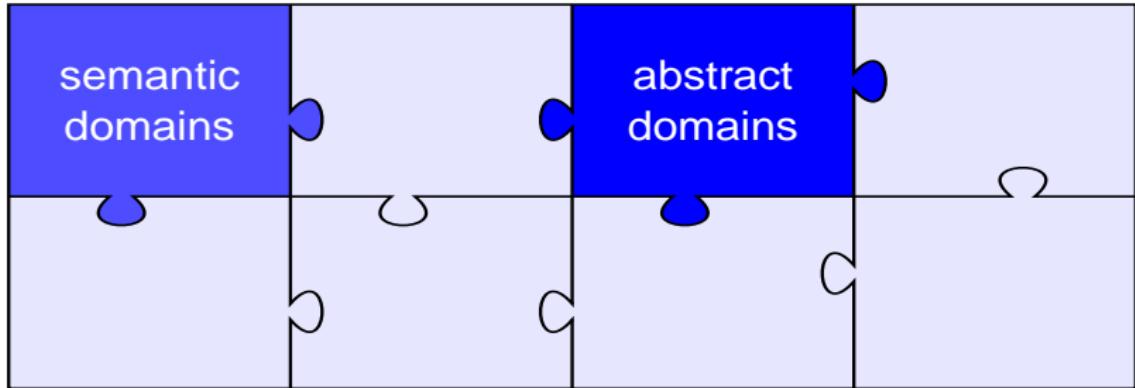
- ▶ A puzzle with 8 pieces,
- ▶ Each piece interacts with its neighbors

Building a certified static analyser



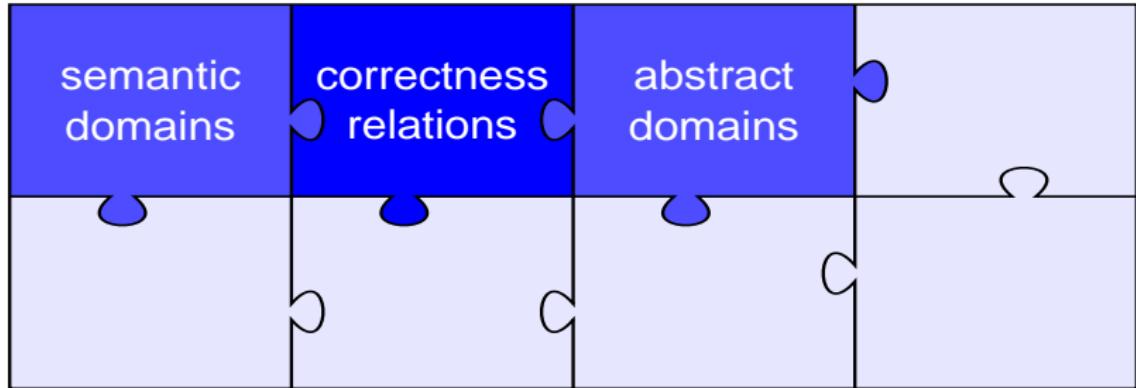
- ▶ Each semantic domain is modeled with a type
- ▶ Following exactly the definitions already seen in a previous slide

Building a certified static analyser



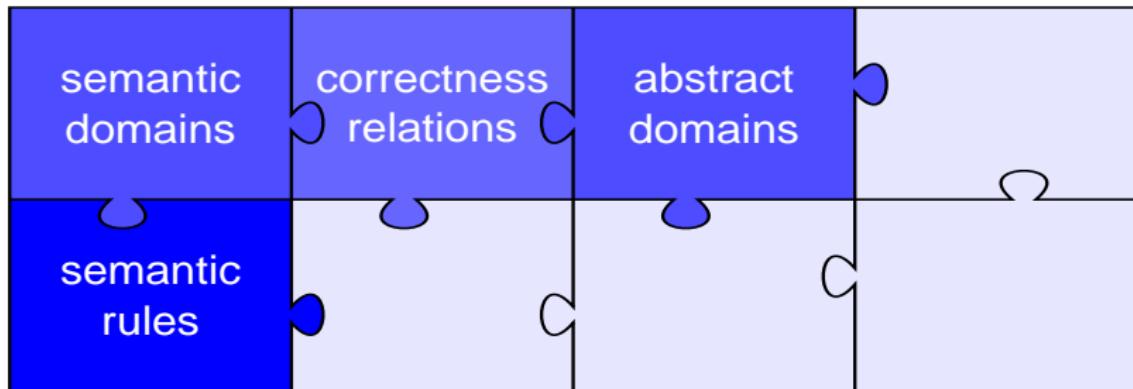
- ▶ Each semantic domain is in relation with an abstract domain
- ▶ an abstract domain is a lattice (formalization of lattices in Coq to follow...)

Building a certified static analyser



- ▶ A relation \sim between State and $\widehat{\text{State}}$
- ▶ $s \sim \widehat{\Sigma}$ interprets as “ $\widehat{\Sigma}$ is a correct approximation of s ”
- ▶ \sim must be monotone :
 $\forall s \in \text{State}, \forall \widehat{\Sigma}_1, \widehat{\Sigma}_2 \in \widehat{\text{State}},$
if $s \sim \widehat{\Sigma}_1$ and $\widehat{\Sigma}_1 \sqsubseteq \widehat{\Sigma}_2$ then $s \sim \widehat{\Sigma}_2$

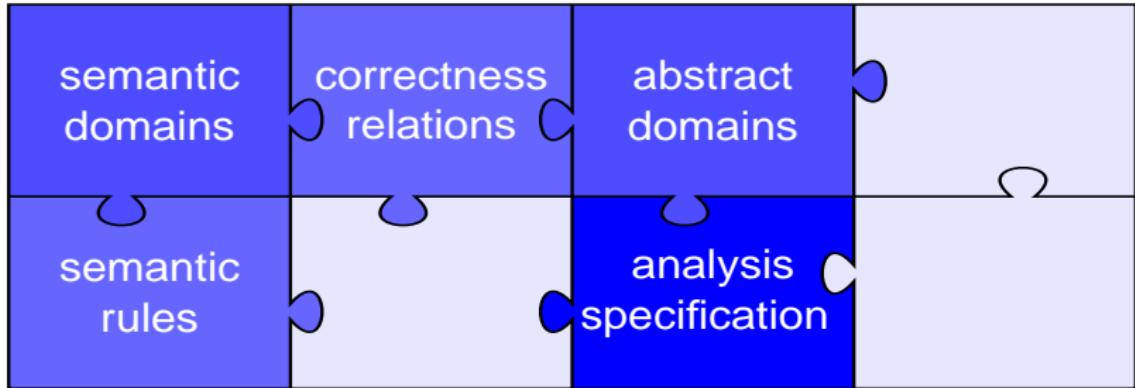
Building a certified static analyser



- ▶ The transition relation $\cdot \Rightarrow \cdot$ is defined using Coq inductive types
- ▶ Collecting semantics :
$$[P] = \{s \mid \exists s_0 \text{ an initial state, with } s_0 \Rightarrow^* s\}$$

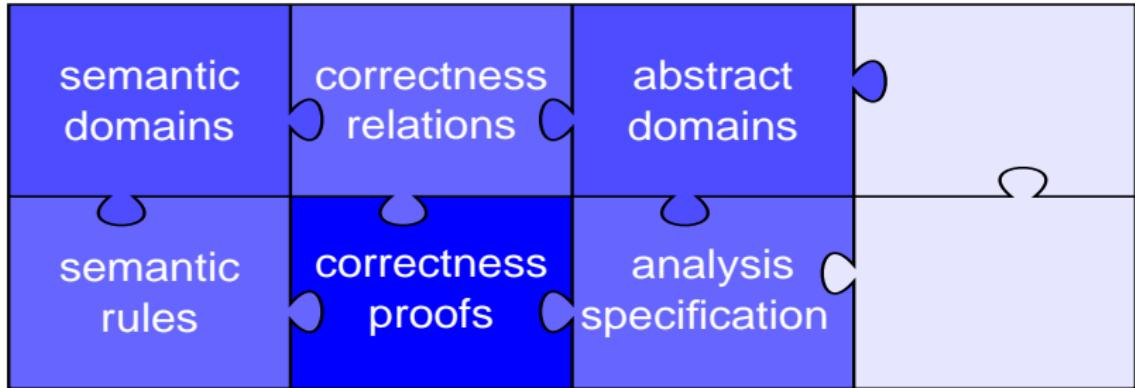
We want to compute a correct approximation of $[P]$

Building a certified static analyser



- ▶ we define a predicate $P \vdash \widehat{\Sigma}$ which imposes a set of constraints on an abstract state $\widehat{\Sigma}$

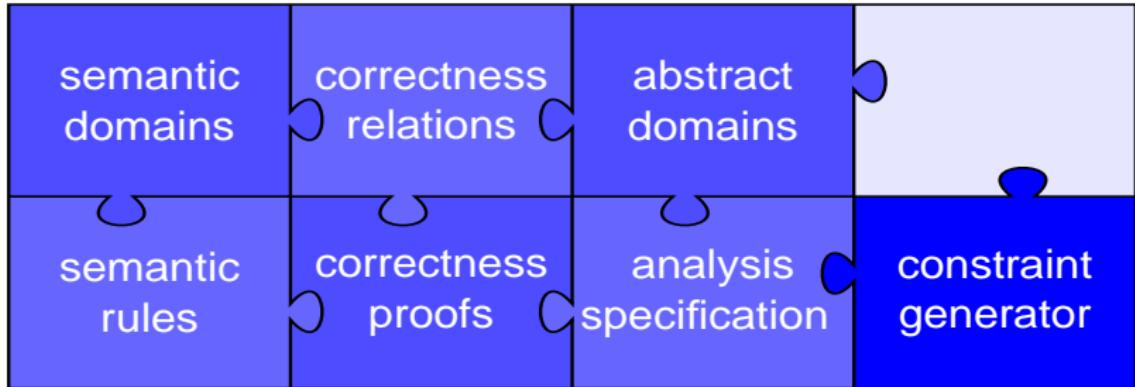
Building a certified static analyser



$$\forall P : \text{Program}, \forall \widehat{\Sigma} : \widehat{\text{State}}, \quad P \vdash \widehat{\Sigma} \Rightarrow [P] \sim \widehat{\Sigma}$$

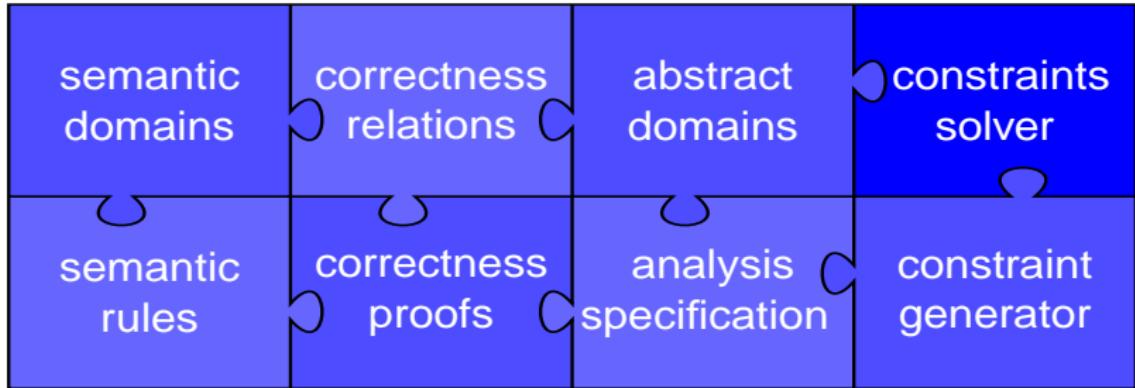
- ▶ One case by instruction
- ▶ With a special treatment for the `invokevirtual`/`return` instructions

Building a certified static analyser



- ▶ Collects all constraint of a given program

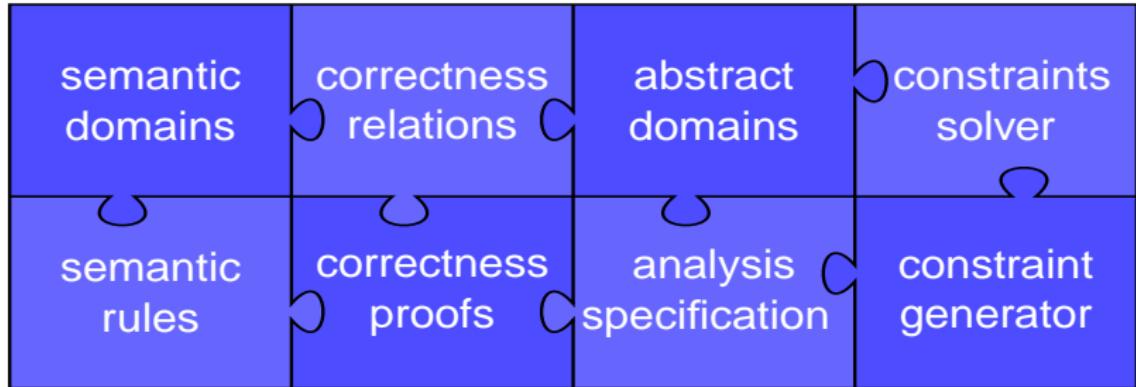
Building a certified static analyser



$$\forall P : \text{Program}, \exists \widehat{\Sigma} : \widehat{\text{State}}, \quad P \vdash \widehat{\Sigma}$$

- ▶ In fact, a stronger result : there exists a smallest solution

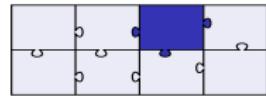
Building a certified static analyser



Final result

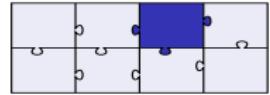
$$\left. \begin{array}{l} \forall P, \forall \widehat{\Sigma}, P \vdash \widehat{\Sigma} \Rightarrow [P] \sim \widehat{\Sigma} \\ \forall P, \exists \widehat{\Sigma}, P \vdash \widehat{\Sigma} \end{array} \right\} \quad \forall P, \exists \widehat{\Sigma}, [P] \sim \widehat{\Sigma}$$

Abstract domains



The lattice type is a big structure :

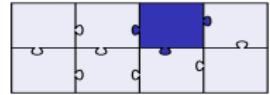
```
Record Lattice [A:Set] : Type := {  
    eq : A → A → Prop;  
  
    order : A → A → Prop;  
  
    join : A → A → A;  
  
    eq_dec : A → A → bool;  
  
    bottom : A;  
  
    top : A;  
}.
```



Abstract domains

The lattice type is a big structure :

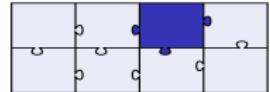
```
Record Lattice [A:Set] : Type := {
  eq : A → A → Prop;
  eq_prop : ...; // eq is an equivalence relation
  order : A → A → Prop;
  order_prop : ...; // order is an order relation
  join : A → A → A;
  join_prop : ...; // join is a correct binary least upper bound
  eq_dec : A → A → bool;
  eq_dec_prop : ...; // eq_dec is a correct equality test
  bottom : A;
  bottom_prop : ...; // bottom is the smallest element
  top : A;
  top_prop : ...; // top is the biggest element
  acc_prop : ...; // ⊓ is well founded (ascending chain condition)
}.
```



Abstract domains

The lattice type is a big structure :

```
Record Lattice [A:Set] : Type := {
  eq : A → A → Prop;
  eq_prop : ...; // eq is an equivalence relation
  order : A → A → Prop;
  order_prop : ...; // order is an order relation
  join : A → A → A;
  join_prop : ...; // join is a correct binary least upper bound
  eq_dec : A → A → bool;
  eq_dec_prop : ...; // eq_dec is a correct equality test
  bottom : A;
  bottom_prop : ...; // bottom is the smallest element
  top : A;
  top_prop : ...; // top is the biggest element
  acc_prop : ...; // ⊓ is well founded (ascending chain condition)
}.
```



A lattice library

- ▶ Two base lattices
 - ▶ Flat lattice of constants
 - ▶ Lattice of sets over a finite subset of integer
- ▶ Four functions to combine lattices
 - ▶ Product of lattice
 - ▶ Sum of lattice
 - ▶ Arrays whose elements live in a lattice and whose size is bounded (efficient functional structure)
 - ▶ List whose elements live in a lattice

This modular construction saves a considerable amount of time and effort.

(array (array (list (finiteSet + constants))))

For this analysis : \times (array (array (array (finiteSet + constants))))
 \times (array (array (finiteSet + constants)))

	b	c			.
u	u	u	u	u	.
p	p	q	q	c	.

Constraint solver

1. A generic fixed point solver

$\forall L : (\text{lattice } A), \forall f : A \rightarrow A, f \text{ monotone},$

$\exists x : A, x \text{ is the least fixed point of } f$

proof : the sequence $\perp, f(\perp), f^2(\perp), \dots$ stabilizes on the least fixed point

2. We use it to solve the functional constraints, using the fact that

$$x \text{ is the least solution of } f_1(x) \sqsubseteq x, \dots, f_n(x) \sqsubseteq x \iff x \text{ is the least fixed point of } \hat{f}_1 \circ \dots \circ \hat{f}_n$$

with $\hat{f}(x) = f(x) \sqcup x$

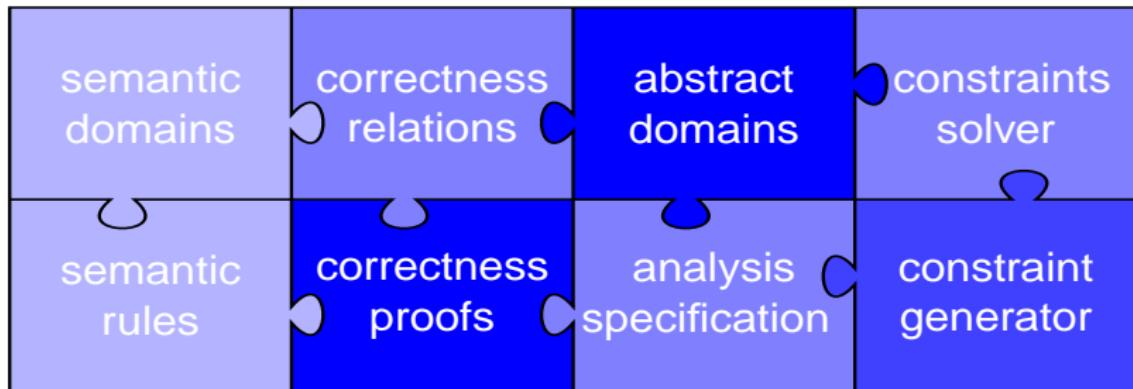
3. Combined with the constraint generator, we obtain

$$\forall P, \exists \widehat{\Sigma}, P \vdash \widehat{\Sigma}$$

Outline

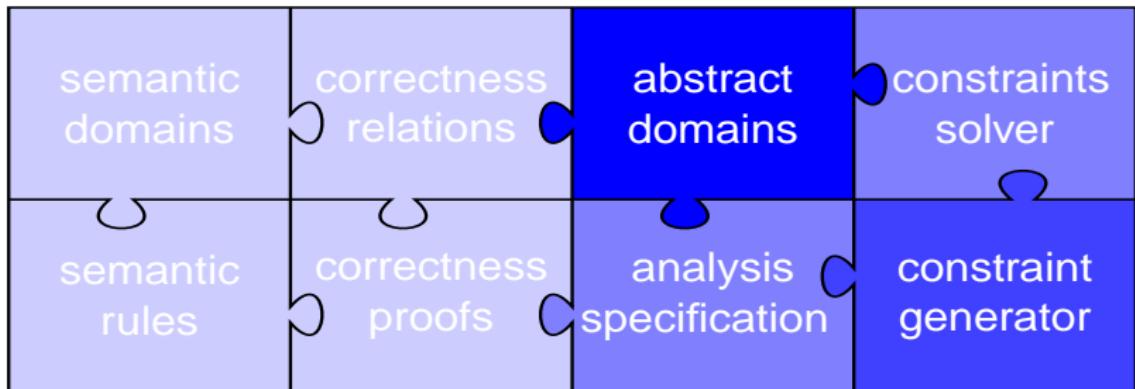
- ▶ Motivation
- ▶ A Static Analysis for Carmel
- ▶ Building a certified static analyser
- ▶ Conclusion

Where is the proof effort ?



- ▶ Most technical part in the lattice library
- ▶ Correctness part does not require specific competences in Coq
- ▶ A majority of proof a reusable to develop others analysis

Where is the programming effort ?



- ▶ The extraction mechanism only keeps the computational content of proofs
- ▶ The corresponding parts require a high attention to obtain an efficient analyser

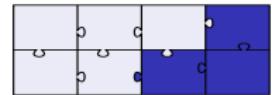
Conclusion on the work

- ▶ We proposed a technique based on the Coq proof assistant
 - ▶ To develop a certified static analyser
 - ▶ To extract a correct analyser in Ocaml
- ▶ We illustrated this technique with a data flow analysis for the Carmel language
 - ▶ 10000 lines of Coq converted in 2000 lines of OCaml
 - ▶ With a reasonable efficiency of the analyser :
 - ▶ About 1 minute to analyse 1000 lines of Carmel byte code

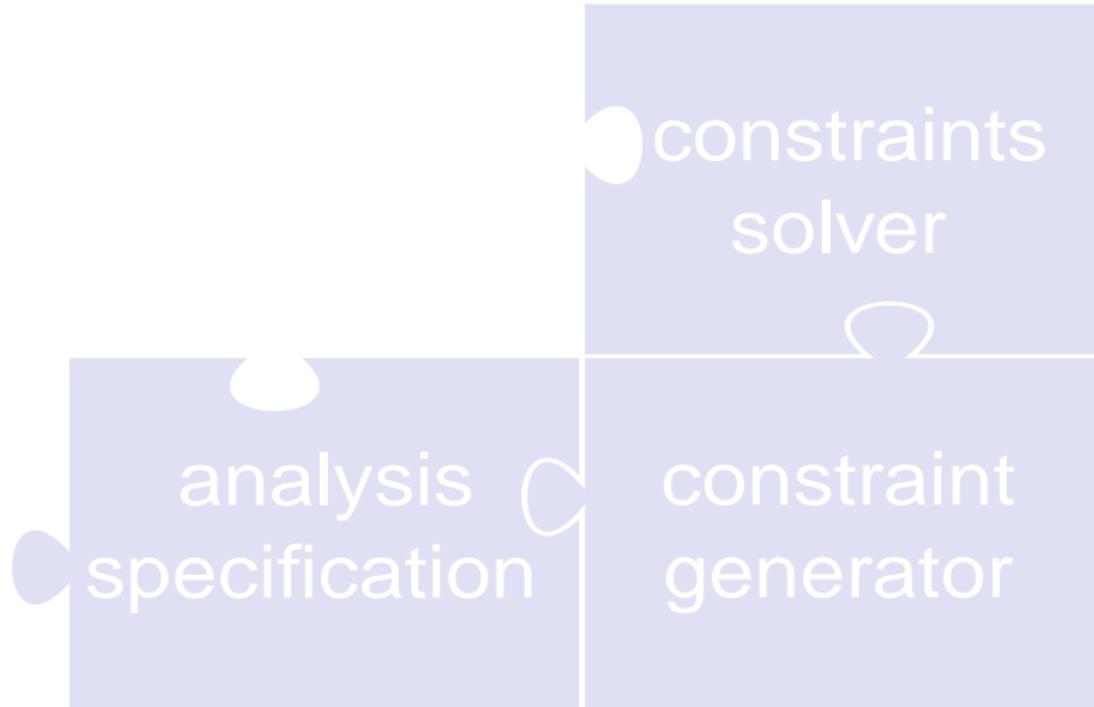
Further works

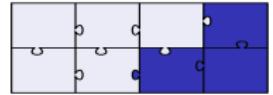
- ▶ Construction of an efficient certified work-set based program instead of the actual naive resolution
 - ▶ This program must be independent of the abstract domains
- ▶ Lattice of infinite height like intervals
- ▶ Automatization of the correctness proof ?
 - ▶ So as to quickly extend the number of language instructions
- ▶ A more extensive use of the abstract interpretation formalism
 - ▶ We must find a compromise between the reusability possibilities and the technical efforts in Coq
- ▶ Application of this technique to others languages

?



Constraint representation



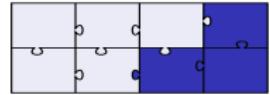


Constraint representation

relational interpretation
(predicate on $\widehat{\text{State}}$)
► Ideal for proofs
► Extraction is compromised

constraints
solver

constraint
generator



Constraint representation

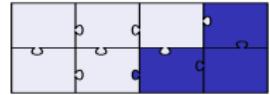
relational interpretation
(predicate on $\widehat{\text{State}}$)

- ▶ Ideal for proofs
- ▶ Extraction is compromised

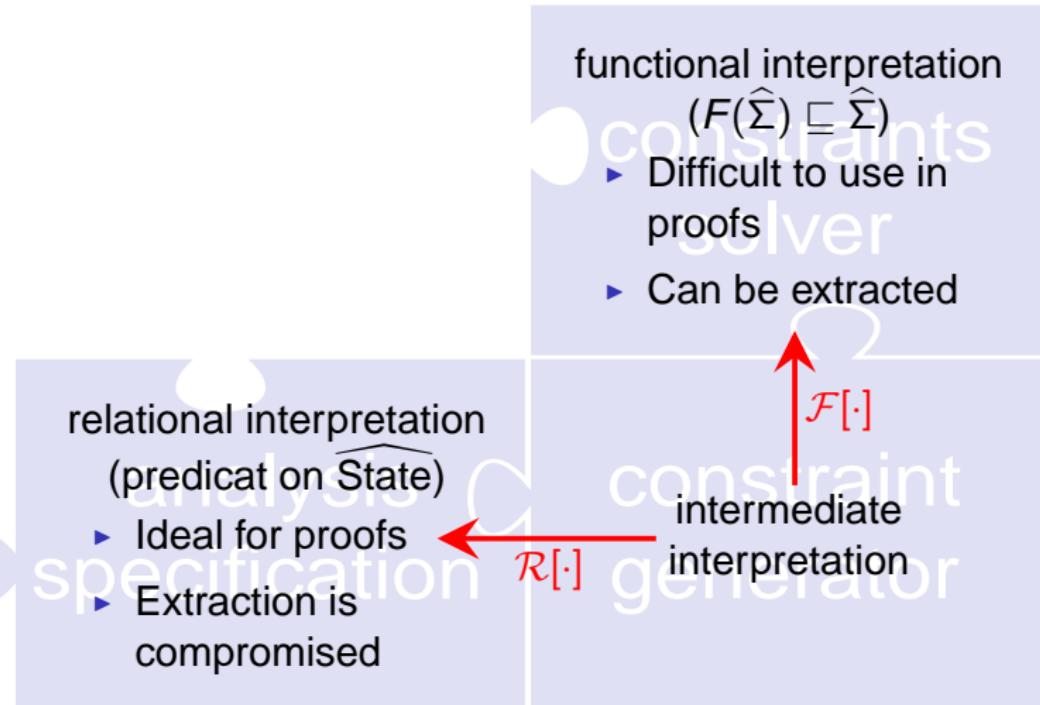
functional interpretation
 $(F(\widehat{\Sigma}) \sqsubseteq \widehat{\Sigma})$

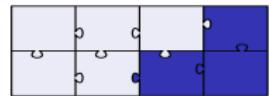
- ▶ Difficult to use in proofs
- ▶ Can be extracted

constraint generator



Constraint representation





Constraint representation

+ a proof of equivalence
 $\forall c : \text{Constraints}, \forall \widehat{\Sigma} : \widehat{\text{State}},$
 $\mathcal{R}[c](\widehat{\Sigma}) \iff \mathcal{F}[c](\widehat{\Sigma}) \sqsubseteq \widehat{\Sigma}$

functional interpretation

$$(\mathcal{F}(\widehat{\Sigma}) \sqsubseteq \widehat{\Sigma})$$

functional interpretation

$$(\mathcal{F}(\widehat{\Sigma}) \sqsubseteq \widehat{\Sigma})$$

- ▶ Difficult to use in proofs
- ▶ Can be extracted

relational interpretation

(predicate on $\widehat{\text{State}}$)

- ▶ Ideal for proofs
- ▶ Extraction is compromised

constraint generator

intermediate interpretation

$$\mathcal{R}[\cdot]$$

$$\mathcal{F}[\cdot]$$

Correctness proof

$$\forall P : \text{Program}, \forall \widehat{\Sigma} : \widehat{\text{State}}, \quad P \vdash \widehat{\Sigma} \implies \llbracket P \rrbracket \sim \widehat{\Sigma}$$

We prove it by well-founded induction on the length of the program execution.

Induction step:

- ▶ for all instructions I , except return

$$\begin{aligned} & \forall P, \forall \widehat{\Sigma} : \widehat{\text{State}}, \quad P \vdash \widehat{\Sigma} \implies \\ & \quad \forall s_1 : \text{State}, \quad s_1 \sim \widehat{\Sigma} \implies \\ & \quad \forall s_2 : \text{State}, \quad [s_1 \Rightarrow_I s_2] \implies s_2 \sim \widehat{\Sigma} \end{aligned}$$

- ▶ for the return instruction

$$\begin{aligned} & \forall P, \forall \widehat{\Sigma} : \widehat{\text{State}}, \quad P \vdash \widehat{\Sigma} \implies \\ & \quad \forall s_1 : \text{State}, \quad \left(\forall s, \quad s \Rightarrow^* s_1 \implies s \sim \widehat{\Sigma} \right) \implies \\ & \quad \forall s_2 : \text{State}, \quad [s_1 \Rightarrow_{\text{return}} s_2] \implies s_2 \sim \widehat{\Sigma} \end{aligned}$$