

On complexity analysis by Quasi-interpretation

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Abstract

We present a survey on methods to analyse the program complexity, based on termination orderings and quasi-interpretations. This method can be implemented to certify the runtime (or space) of programs. We demonstrate that the class of functions computed by first order functional programs over free algebras which terminate by Permutation Path Ordering (resp. Lexicographic Path Ordering) and admit a quasi-interpretation bounded by a polynomial, is exactly the class of functions computable in polynomial time (resp. space).

1 Introduction

This paper is part of a general investigation on program complexity analysis. We have introduced program quasi-interpretations, see [25, 26, 27, 7, 5], in order to bound the size of program inputs and outputs. Combined with termination methods, we can determine the runtime (or space) of a program.

In this survey, we consider first order functional programs for which termination is established by using recursive path orderings. Suppose that a program admits a quasi-interpretation which is bounded by a polynomial. We obtain different resource upper bounds based on termination proofs.

- If the program terminates by permutation path ordering, then it is computable in polynomial time. It is worth noticing that we have to compute the program by call-by value semantics with a cache.
- If the program terminates by lexicographic path ordering, then the computation consumes a polynomial space.

From a practical point of view, the bottom line is this. The complexity analysis can be performed by static analysis and can be partially automatized. Moreover, we can build resource certificates similar to the idea behind proof-carrying code techniques. Indeed, Krishnamoorthy and Narendran in [20] have proved that termination by recursive path orderings is NP-complete. To find a quasi-interpretation is not too difficult in general, because the program denotation turns out to be a good candidate, see [28]. Moreover, Amadio shows in [1] that synthesis max-plus quasi-interpretations is NP-hard. These ideas have been applied in a resource byte-code verifier [2].

From a theoretical point of view, we characterize the class PTIME and PSPACE. This work is related to Bellantoni and Cook [4], Leivant [22] and

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Marion [23] ideas to delineate complexity classes. However most of the complexity class characterizations focus on functions and not on algorithms. A consequence of this kind of extensional approaches is the fact they fail to say something meaningful about programming theory. For this reason, we are more interested by the algorithms than by functions. Hence, we move from extensional characterizations to intensional ones. Such intensional approach have actually been studied by Caseiro [8] and Hofmann [18].

2 First order functional programming

Throughout the following discussion, we consider three disjoint sets $\mathcal{X}, \mathcal{F}, \mathcal{C}$ of variables, function symbols and constructors.

2.1 Syntax of programs

Definition 1. The sets of terms, patterns and function rules are defined in the following way:

(Constructor terms)	$\mathcal{T}(\mathcal{C}) \ni u$	$::= \mathbf{c} \mid \mathbf{c}(u_1, \dots, u_n)$
(Ground terms)	$\mathcal{T}(\mathcal{C}, \mathcal{F}) \ni s$	$::= \mathbf{c} \mid \mathbf{c}(s_1, \dots, s_n) \mid \mathbf{f}(s_1, \dots, s_n)$
(terms)	$\mathcal{T}(\mathcal{C}, \mathcal{F}, \mathcal{X}) \ni t$	$::= \mathbf{c} \mid x \mid \mathbf{c}(t_1, \dots, t_n) \mid \mathbf{f}(t_1, \dots, t_n)$
(patterns)	$\mathcal{P} \ni p$	$::= \mathbf{c} \mid x \mid \mathbf{c}(p_1, \dots, p_n)$
(rules)	$\mathcal{D} \ni d$	$::= \mathbf{f}(p_1, \dots, p_n) \rightarrow t$

where $x \in \mathcal{X}$, $\mathbf{f} \in \mathcal{F}$, and $\mathbf{c} \in \mathcal{C}^1$. The size $|t|$ of a term t is the number of symbols in t .

Definition 2. A program is a quintuplet $\mathbf{main} = \langle \mathcal{X}, \mathcal{C}, \mathcal{F}, \mathcal{E}, \mathbf{f} \rangle$ such that:

- \mathcal{E} is a set of \mathcal{D} -rules.
- Each variable in the right-hand side of a rule also appears in the left hand side of the same rule.
- \mathbf{f} is the main function symbol of \mathbf{main} .

All along the paper, we assume that the set of rules is implicit and we use \mathbf{main} to denote the program and its main symbol.

2.2 Semantics

The semantics is given by the term rewriting system \mathcal{E} . We recall briefly some vocabulary of rewriting theories. For further details, one might consult Dershowitz and Jouannaud's survey [14] from which we take the notations. The rewriting relation \rightarrow induced by a program \mathbf{main} is defined as follows $t \rightarrow s$ if s is obtained from t by applying one of the rules of \mathcal{E} . The relation $\overset{*}{\rightarrow}$ is the reflexive-transitive closure of \rightarrow . Lastly, $t \overset{!}{\rightarrow} s$ means that $t \overset{*}{\rightarrow} s$ and s is in normal form, *i.e.* no other rule may be applied. A ground (resp. constructor) substitution is a substitution from \mathcal{X} to $\mathcal{T}(\mathcal{C}, \mathcal{F})$ (resp. $\mathcal{T}(\mathcal{C})$).

¹We shall use type writer font for function symbol and bold face font for constructors.

We now give the semantics of confluent programs, that is programs for which the associated rewrite system is confluent. The domain of interpretation is the constructor algebra $\mathcal{T}(\mathcal{C})$.

Definition 3. Let `main` be a confluent program. The function computed by `main` is the partial function $\llbracket \text{main} \rrbracket : \mathcal{T}(\mathcal{C})^n \rightarrow \mathcal{T}(\mathcal{C})$ where n is the arity of `main` which is defined as follows. For all $u_i \in \mathcal{T}(\mathcal{C})$, $\llbracket \text{main} \rrbracket(u_1, \dots, u_n) = v$ iff `main`(u_1, \dots, u_n) $\xrightarrow{!} v$ with $v \in \mathcal{T}(\mathcal{C})$. Note that due to the form of the rules a constructor term is a normal form ; as the program is confluent, it is uniquely defined. Otherwise, that is if there is no such normal form, $\llbracket \text{main} \rrbracket(u_1, \dots, u_n)$ is undefined.

3 Orderings on terms

The use of orderings has been widely studied in order to prove the termination of term rewriting systems. Among them, we are interested here by path orderings and especially the *Multiset Path Ordering (MPO)* and the *Lexicographic Path Ordering (LPO)* respectively introduced by Plaisted [29] and Dershowitz [13] and by Kamin and Lévy [19]. We briefly describe them, together with some basic properties we shall use later on.

3.1 Path orderings

Definition 4. Let $M = \{m_1, \dots, m_p\}$ and $N = \{n_1, \dots, n_p\}$ be two multisets with the same number of elements and \prec be an ordering over these elements. The permutation extension of \prec over multisets is defined in the following way: $M \prec^m N$ if and only if there exists a permutation π such that

- $\forall 1 \leq i \leq p, m_i \preceq n_{\pi(i)}$.
- $\exists 1 \leq j \leq n$ such that $m_j \prec n_{\pi(j)}$.

Definition 5. Let \prec be a term ordering. We note \prec^l its usual lexicographic extension.

A precedence $\preceq_{\mathcal{F}}$ (strict precedence $\prec_{\mathcal{F}}$) is an ordering (strict ordering) on the set \mathcal{F} of function symbols. Define the equivalence relation $\approx_{\mathcal{F}}$ as $\mathbf{f} \approx_{\mathcal{F}} \mathbf{g}$ iff $\mathbf{f} \preceq_{\mathcal{F}} \mathbf{g}$ and $\mathbf{g} \preceq_{\mathcal{F}} \mathbf{f}$. This order $\preceq_{\mathcal{F}}$ on function symbol extends canonically on $\mathcal{C} \cup \mathcal{F}$ by saying that

- constructors are smaller than function symbols,
- two constructors are incomparable.

It is worth noting that constructors are minimal symbols with respect to $\preceq_{\mathcal{F}}$. Moreover, we will consider that constructors and all variables are incomparable.

Definition 6. Given a precedence $\preceq_{\mathcal{F}}$, we define the Multiset Path Ordering and the Lexicographic Path Ordering by the following (inductive) rules. x should be taken in $\{m, l\}$.

$$\frac{\{s_1, \dots, s_n\} \prec^m \{t_1, \dots, t_n\}}{\mathbf{c}(s_1, \dots, s_n) \prec_{xpo} \mathbf{c}(t_1, \dots, t_n)} \mathbf{c} \in \mathcal{C} \quad \frac{s \prec_{xpo} t_i}{s \prec_{xpo} f(\dots, t_i, \dots)} f \in \mathcal{F} \cup \mathcal{C}$$

$$\frac{s_i \prec_{xpo} \mathbf{f}(t_1, \dots, t_n) \quad g \prec_{\mathcal{F}} \mathbf{f}}{g(s_1, \dots, s_m) \prec_{xpo} \mathbf{f}(t_1, \dots, t_n)} g \in \mathcal{F} \cup \mathcal{C}$$

$$\frac{(s_1, \dots, s_n) \prec_{xpo}^x (t_1, \dots, t_n) \quad \mathbf{f} \approx_{\mathcal{F}} \mathbf{g} \quad s_j \prec_{xpo} \mathbf{f}(t_1, \dots, t_n)}{\mathbf{g}(s_1, \dots, s_n) \prec_{xpo} \mathbf{f}(t_1, \dots, t_n)}$$

Definition 7. A program is terminating by *MPO* (resp. *LPO*) if there is a precedence on \mathcal{F} such that for each rule $l \rightarrow r$ of \mathcal{E} , we have $r \prec_{mpo} l$ (resp. \prec_{lpo}).

Remark 8. Note that these orderings are special cases of the more general Recursive Path Ordering (RPO) with status *à la* Kamin & Lévy [19] where the status of each constructor is permutation and the status of functions symbols is either permutation (MPO) or lexicographic (LPO).

Note also that they doesn't exactly define the usual MPO or LPO but can easily be shown to capture the same functions (but not necessarily the same algorithms). Especially, the permutation ordering we use for MPO is a restriction of the multiset ordering usually used, but the resulting ordering is nonetheless as powerful as the original one (see [27]).

Theorem 9 (Hofbauer [17], Cichon [10]). *The set of functions computed by programs that terminate with respect to MPO is exactly the set of primitive recursive functions.*

Theorem 10 (Weiermann [31]). *The set of functions computed by programs that terminate with respect to LPO is exactly the set of multiply-recursive functions.*

3.2 Polynomial quasi-interpretation

Quasi-interpretations have been introduced by Bonfante [5] and by Marion and Moyen [27, 24].

Definition 11 (Quasi-interpretations). A *polynomial quasi-interpretation* (or shorter in this paper, quasi-interpretation) of a symbol $a \in \mathcal{F} \cup \mathcal{C}$ whose arity is n is a function $\llbracket a \rrbracket : \mathbf{R}^{+n} \rightarrow \mathbf{R}^+$ such that :

- $\llbracket a \rrbracket$ is bounded by a polynomial.
- $\llbracket a \rrbracket(X_1, \dots, X_n) \geq X_i$ for all $1 \leq i \leq n$.
- $\llbracket a \rrbracket$ is increasing (not necessarily strictly) with respect to each variable.

As a consequence, the quasi-interpretation of a constant is a positive number.

We extend a quasi-interpretation $\llbracket - \rrbracket$ to terms canonically: $\llbracket f(t_1, \dots, t_n) \rrbracket = \llbracket f \rrbracket(\llbracket t_1 \rrbracket, \dots, \llbracket t_n \rrbracket)$ where we take the identity for variables.

Moreover, quasi-interpretation are classified according to the quasi-interpretation of constructors. A quasi-interpretation is

- of **kind 0** if $\langle \mathbf{c} \rangle (X_1, \dots, X_n) = \sum_{i=1}^n X_i + b, b \geq 1$;
- of **kind 1** if $\langle \mathbf{c} \rangle$ is a polynomial whose degree is at most 1 in each variable;
- of **kind 2** if $\langle \mathbf{c} \rangle$ is any polynomial.

If nothing is specified, we will always consider quasi-interpretation to be of kind 0.

Definition 12. $\langle - \rangle$ is a quasi-interpretation of a program **main** if for each rule $l \rightarrow r \in \mathcal{E}(\mathbf{main})$ and for each closed substitution σ , $\langle l\sigma \rangle \geq \langle r\sigma \rangle$.

Remark 13. Quasi-interpretations do not ensure termination. Indeed, the rule $\mathbf{f}(x) \rightarrow \mathbf{f}(x)$ admits a quasi-interpretation but doesn't terminate.

Moreover, quasi-interpretation do not give enough information to decide termination as stated in the following theorem.

Theorem 14. *Let main be a system admitting a quasi-interpretation (any kind). It is undecidable to know whether the system terminates or not.*

Proof. Senizergues proved in [30] that the termination of non-increasing semi-Thue systems is undecidable. But, these semi-Thue systems are a particular case of rewriting systems with a quasi-interpretation (simply take the identity polynomial for the unary symbols and 1 for the unique constant ϵ). The theorem follows immediately. \square

But the quasi-interpretation give nonetheless some information about the complexity of the program. Indeed, a program admitting a quasi-interpretation (any kind) either terminates in triple exponential time or will loop forever, thus leading to a potential runtime detection of non-termination.

3.3 Interpretations

Definition 15. An interpretation is a quasi-interpretation with the following restrictions:

- (i) $\langle f \rangle$ is a polynomial,
- (ii) $\langle f \rangle (X_1, \dots, X_n) > X_i$,
- (iii) $\langle l\sigma \rangle > \langle r\sigma \rangle$.

Programs admitting an interpretation terminate. This sort of termination proof, by polynomial interpretations, was introduced by Lankford [21] and turns out to be a useful tool for proving termination (see [9, 15] among other).

The kind of an interpretation is determined according to the interpretation of constructors, in the same way as for quasi-interpretations.

Theorem 16 (Bonfante, Cichon, Marion and Touzet [6]). *According to its kind, interpretation characterise the following complexity classes:*

<i>kind of the interpretation</i>	<i>confluent system</i>	<i>non-confluent system</i>
0	P _{TIME}	NP _{TIME}
1	E _{TIME}	NE _{TIME}
2	E ₂ TIME	NE ₂ TIME

Where non-confluent systems are defined following Gurevich and Grädel [16]:

Definition 17 (Non confluent programs). Given a quintuplet $\mathbf{main} = \langle \mathcal{X}, \mathcal{C}, \mathcal{F}, \mathcal{E}, \mathbf{f} \rangle$ and an order \prec on constructor terms—actually, this order should be computable in polynomial time—, the semantics of \mathbf{main} , that is $\llbracket \mathbf{main} \rrbracket : \mathcal{T}(\mathcal{C})^n \rightarrow \mathcal{T}(\mathcal{C})$ where n is the arity of \mathbf{main} is defined as follows. For all $u_i \in \mathcal{T}(\mathcal{C})$,

$$\llbracket \mathbf{main} \rrbracket(u_1, \dots, u_n) = \max_{\prec} \{v \in \mathcal{T}(\mathcal{C}) \mid \mathbf{main}(u_1, \dots, u_n) \xrightarrow{!} v\}.$$

4 Termination orderings and quasi-interpretations

4.1 MPO and quasi-interpretations

Definition 18. A MPO^{QI} -program of kind k is a MPO-program that admits a quasi-interpretation of kind k .

Theorem 19 (Marion & Moyen [27]). *The set of functions computed by MPO^{QI} -programs is exactly the set of functions computable in*

- *polynomial time for kind 0;*
- *exponential time for kind 1;*
- *double exponential time for kind 2.*

Example 20. Given a list l , $\text{sort}(l)$ sorts the elements of l . The algorithm is the insertion sort. Constructors are $\mathcal{C} = \{\mathbf{tt}, \mathbf{ff}, \mathbf{0}, \mathbf{S}, \mathbf{nil}, \mathbf{cons}\}$.

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if tt then x else y → x
if ff then x else y → y
  0 < S(y) → tt
  x < 0 → ff
  S(x) < S(y) → x < y
insert(a, nil) → cons(a, nil)
insert(a, cons(b, l)) → if a < b then cons(a, cons(b, l))
                        else cons(b, insert(a, l))
sort(nil) → nil
sort(cons(a, l)) → insert(a, sort(l))

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This program terminates by MPO with the precedence $\text{if} \prec_{\mathcal{F}} - < - \prec_{\mathcal{F}} \text{insert} \prec_{\mathcal{F}} \text{sort}$. It admits the following quasi-interpretation (of kind 0):

- $\langle \mathbf{tt} \rangle = \langle \mathbf{ff} \rangle = \langle \mathbf{0} \rangle = \langle \mathbf{nil} \rangle = 1$
- $\langle \mathbf{S} \rangle(X) = X + 1$
- $\langle \mathbf{cons} \rangle(X, Y) = \langle \mathbf{insert} \rangle(X, Y) = X + Y + 1$
- $\langle \mathbf{sort} \rangle(X) = X$

So, it computes a function of PTIME.

Example 21. The following algorithm computes the length of the longest common subsequence of two sequences.

$$\begin{aligned}
\text{lcs}(\epsilon, y) &\rightarrow \mathbf{0} \\
\text{lcs}(x, \epsilon) &\rightarrow \mathbf{0} \\
\text{lcs}(\mathbf{i}(x), \mathbf{i}(y)) &\rightarrow \mathbf{S}(\text{lcs}(x, y)) \\
\text{lcs}(\mathbf{i}(x), \mathbf{j}(y)) &\rightarrow \max(\text{lcs}(x, \mathbf{j}(y)), \text{lcs}(\mathbf{i}(x), y)) & \mathbf{i} \neq \mathbf{j} \\
\max(n, \mathbf{0}) &\rightarrow n \\
\max(\mathbf{0}, m) &\rightarrow m \\
\max(\mathbf{S}(n), \mathbf{S}(m)) &\rightarrow \mathbf{S}(\max(n, m)) & \mathbf{i} \in \{\mathbf{a}, \mathbf{b}\}
\end{aligned}$$

It terminates by MPO with the precedence $\max \prec_{\mathcal{F}} \text{lcs}$ and it admits the following quasi-interpretation (of kind 0):

- $\langle \epsilon \rangle = \langle \mathbf{0} \rangle = 1$
- $\langle \mathbf{a} \rangle(X) = \langle \mathbf{b} \rangle(X) = \langle \mathbf{S} \rangle(X) = X + 1$
- $\langle \text{lcs} \rangle(X, Y) = \langle \max \rangle(X, Y) = \max(X, Y)$

So, it computes a function of PTIME.

This latest example is particularly interesting. Indeed, if one apply the rules of the program, one may get a exponentially long derivation chain, but the theorem states that it can be computed in polynomial time. Actually, one should be careful not to confuse the algorithm and the function it computes. This function (longest common subsequence) is a classical textbook example of so called “dynamic programming” (see chapter 16 of [12]) and can in this way be computed in polynomial time.

So, the theorem doesn’t characterise the complexity of the algorithm, which we should call its *explicit* complexity but the complexity of the function computed by this algorithm, which we should call its *implicit* complexity.

Of course, one may ask whether the polynomial bound is achievable or not (we mean automatically achievable from the program). And it actually is, simply by simulating at runtime the dynamic programming technique, that is storing each and every result of a function call in a table and avoiding to recompute the same function call if it’s already in the table. This technique is inspired from Jones’ rereading of Cook classical technique over 2 way push-down automatas ([11, 3]) and is called memoisation.

This memoisation-evaluation of the program is implemented by the cache-interpreter of Figure 1. In the general case, memoisation is not used because one cannot decide which result will be reused and the cache may become too big to be really useful. In our particular case, the termination ordering gives enough informations on the structure of the program to allow minimisation of the cach [25].

4.2 LPO and quasi-interpretations

Definition 22. A LPO^{QI} -program of kind k is a LPO-program that admits a quasi-interpretation of kind k .

$$\begin{array}{c}
\frac{x\sigma = v}{\mathcal{E}, \sigma \vdash \langle C, x \rangle \rightarrow \langle C, v \rangle} \text{ (Variable)} \\
\\
\frac{\mathbf{c} \in \mathcal{C} \quad \mathcal{E}, \sigma \vdash \langle C_{i-1}, t_i \rangle \rightarrow \langle C_i, v_i \rangle}{\mathcal{E}, \sigma \vdash \langle C_0, \mathbf{c}(t_1, \dots, t_n) \rangle \rightarrow \langle C_n, \mathbf{c}(v_1, \dots, v_n) \rangle} \text{ (Constructor)} \\
\\
\frac{\mathbf{f} \in \mathcal{F} \quad \mathcal{E}, \sigma \vdash \langle C_{i-1}, t_i \rangle \rightarrow \langle C_i, v_i \rangle \quad (\mathbf{f}(v_1, \dots, v_n), v) \in C_n}{\mathcal{E}, \sigma \vdash \langle C_0, \mathbf{f}(t_1, \dots, t_n) \rangle \rightarrow \langle C_n, v \rangle} \text{ (Cach reading)} \\
\\
\frac{\mathcal{E}, \sigma \vdash \langle C_{i-1}, t_i \rangle \rightarrow \langle C_i, v_i \rangle \quad \mathbf{f}(p_1, \dots, p_n) \rightarrow r \in \mathcal{E} \quad p_i \sigma' = v_i \quad \mathcal{E}, \sigma' \vdash \langle C_n, r \rangle \rightarrow \langle C, v \rangle}{\mathcal{E}, \sigma \vdash \langle C_0, \mathbf{f}(t_1, \dots, t_n) \rangle \rightarrow \langle C \bigcup (\mathbf{f}(v_1, \dots, v_n), v) \rangle} \text{ (Cach push)}
\end{array}$$

Figure 1: Evaluation of a rewriting system with memorization of intermediate evaluations

Theorem 23 (Bonfante, Marion & Moyen [7]). *The set of functions computed by LPO^{QI} -programs is exactly the set of functions computable in*

- polynomial space for kind 0;
- exponential space for kind 1;
- double exponential space for kind 2.

Example 24. The Quantified Boolean Formula (QBF) is the problem of the validity of a boolean formula with quantifiers over propositional variables. It is well-known to be PSPACE complete. Without loss of generality, we restrict formulae to \neg, \vee, \exists . It can be solved by the following rules:

$$\begin{array}{ll}
\text{not}(\mathbf{tt}) \rightarrow \mathbf{ff} & \text{in}(x, \mathbf{nil}) \rightarrow \mathbf{ff} \\
\text{not}(\mathbf{ff}) \rightarrow \mathbf{tt} & \text{in}(x, \mathbf{cons}(a, l)) \rightarrow \text{or}(x = a, \text{in}(x, l)) \\
\text{or}(\mathbf{tt}, x) \rightarrow \mathbf{tt} & \\
\text{or}(\mathbf{ff}, x) \rightarrow x & \text{main}(\phi) \rightarrow \text{ver}(\phi, \mathbf{nil}) \\
\mathbf{0} = \mathbf{0} \rightarrow \mathbf{tt} & \text{ver}(\mathbf{Var}(x), t) \rightarrow \text{in}(x, t) \\
\mathbf{S}(x) = \mathbf{0} \rightarrow \mathbf{ff} & \text{ver}(\mathbf{Not}(\phi), t) \rightarrow \text{not}(\text{ver}(\phi, t)) \\
\mathbf{0} = \mathbf{S}(y) \rightarrow \mathbf{ff} & \text{ver}(\mathbf{Or}(\phi_1, \phi_2), t) \rightarrow \text{or}(\text{ver}(\phi_1, t), \text{ver}(\phi_2, t)) \\
\mathbf{S}(x) = \mathbf{S}(y) \rightarrow x = y & \text{ver}(\mathbf{Exists}(n, \phi), t) \rightarrow \text{or}(\text{ver}(\phi, \mathbf{cons}(n, t)), \text{ver}(\phi, t))
\end{array}$$

These rules are ordered by LPO by putting $\{\text{not}, \text{or}, =_-\} \prec_{\mathcal{F}} \text{in} \prec_{\mathcal{F}} \text{ver} \prec_{\mathcal{F}} \text{main}$.

They admit the following quasi-interpretations (of kind 0):

- $\langle \mathbf{c} \rangle (X_1, \dots, X_n) = 1 + \sum_{i=1}^n X_i$, for each n-ary constructor,
- $\langle \text{ver} \rangle (\Phi, T) = \Phi + T$, $\langle \text{main} \rangle (\Phi) = \Phi + 1$,
- $\langle \mathbf{f} \rangle (X_1, \dots, X_n) = \max_{i=1}^n X_i$, for the other function symbols.

So the function is PSPACE-computable.

5 Further results

We briefly present some new results.

Theorem 25. *Functions computed by non confluent programs that admit a quasi-interpretation of kind 0 and a MPO proof of termination are exactly PSPACE functions.*

This result is quite surprising. Indeed, by adding non-confluence (that is, non-determinism) to PTIME, we expected to characterise NP TIME. Here, we reach a step above and characterise PSPACE (actually, we do characterize NPSPACE, but these two classes are equal). Moreover, at this point, termination by MPO or LPO doesn't change the class characterised whereas it has always been the case otherwise.

Definition 26. A *strict quasi-interpretation* is a quasi-interpretation where for any symbols f , one has $(|f|)(X_1, \dots, X_k) > X_i$ for all $i \leq n$.

Strict quasi-interpretation still don't ensure termination.

Theorem 27. *The set of functions computed by rewrite systems such that:*

- *it admits a strict quasi-interpretation,*
- *it terminates*

is exactly the set of PSPACE functions.

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